

Lecture 12

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Example 1 Let us consider the LASSO problem again:

$$\min_{\mathbf{x}} \left\{ \frac{1}{2} \|\mathbf{Ax} - \mathbf{b}\|_2^2 + \lambda \|\mathbf{x}\|_1 \right\}. \quad (1)$$

- $f(\mathbf{x}) = \frac{1}{2} \|\mathbf{Ax} - \mathbf{b}\|_2^2$ is convex and β -smooth.
- $b(\mathbf{x}) = \lambda \|\mathbf{x}\|_1$ is convex and non-smooth.
- Proximal Operator:

$$\text{prox}_{\gamma \|\mathbf{x}\|_1}(\mathbf{z}) = \arg \min_{\mathbf{x}} \left\{ \frac{1}{2\gamma} \|\mathbf{x} - \mathbf{z}\|_2^2 + \lambda \|\mathbf{x}\|_1 \right\} \quad (2)$$

$$= \arg \min_{\mathbf{x}} \sum_{i=1}^n \left\{ \frac{1}{2\gamma} (x_i - z_i)^2 + \lambda |x_i| \right\}. \quad (3)$$

- For each $i = 1, \dots, n$, we need to solve

$$\arg \min_{x_i} \left\{ \frac{1}{2\gamma} (x_i - z_i)^2 + \lambda |x_i| \right\} := \phi(x_i). \quad (4)$$

If $x_i > 0$, then set $\phi'(x_i) = 0$ it has $x_i^* = z_i - \gamma\lambda$. If $x_i < 0$, then $x_i^* = z_i + \gamma\lambda$. If $x_j = 0$, then we need $0 \in \partial\phi(0)$. So, $0 \in \frac{1}{\gamma}(0 - z_i) + \lambda\partial|0|$. So, $\frac{z_i}{\gamma\lambda} \in \partial|0| = [-1, 1]$. Thus,

$$x_i = \begin{cases} z_i - \gamma\lambda & z_i > \gamma\lambda, \\ 0, & |z_i| \leq \gamma\lambda, \\ z_i + \gamma\lambda & z_i < -\gamma\lambda. \end{cases} \quad (5)$$

This is called the soft thresholding function.

- $\text{prox}_{\gamma \|\mathbf{x}\|_1}(\mathbf{z}) = \text{sign}(\mathbf{z})(|\mathbf{z}| - \gamma\lambda)_+$.
- Go back to LASSO. $\beta = \lambda_{\max}(A^T A)$, $\nabla f(\mathbf{x}) = A^T(\mathbf{Ax} - \mathbf{b})$.
- Algorithm:

$$\mathbf{z}^t = \mathbf{x}^t - \frac{1}{\lambda_{\max}(A^T A)} A^T(\mathbf{Ax} - \mathbf{b}) = \left(I - \frac{A^T A}{\lambda_{\max}(A^T A)} \right) \mathbf{x}^t + \frac{A^T \mathbf{b}}{\lambda_{\max}(A^T A)},$$

$$\mathbf{x}^{t+1} = \text{prox}_{\frac{\lambda}{\lambda_{\max}(A^T A)} \|\mathbf{x}\|_1}(\mathbf{z}^t) = \text{sign}(\mathbf{z}^t) \left(|\mathbf{z}^t| - \frac{\lambda}{\lambda_{\max}(A^T A)} \right)_+.$$

0.1 Convergence Theory

Let us define $\mathbf{x}^+ = \text{prox}_{\gamma g}(\mathbf{x} - \gamma \nabla f(\mathbf{x}))$ and $G_\gamma(\mathbf{x}) = \frac{1}{\gamma}(\mathbf{x} - \mathbf{x}^+)$.

Insights: if $\mathbf{x}^+ = \mathbf{x} - \gamma \nabla f(\mathbf{x})$, then $\frac{1}{\gamma}(\mathbf{x} - \mathbf{x}^+) = \nabla f(\mathbf{x})$. We hope G_γ has similar behaviours with $\nabla f(\mathbf{x})$.

Lemma 1 *let $h(\mathbf{x}) = f(\mathbf{x}) + g(\mathbf{x})$, $g(\mathbf{x})$ is convex and non-smooth, $f(\mathbf{x})$ is smooth. \mathbf{x}^* is a local minimal point of h , then*

$$-\nabla f(\mathbf{x}^*) \in \partial g(\mathbf{x}^*). \quad (6)$$

Lemma 2 *$G_\gamma(\mathbf{x}) = 0$ if and only if $0 \in \partial h(\mathbf{x})$. This implies \mathbf{x} is a global minimum.*

Proof 1 *We know that \mathbf{x}^+ minimizes*

$$\frac{1}{2\gamma} \|\mathbf{z} - (x - \gamma f(\mathbf{x}))\|^2 + g(\mathbf{z})$$

by definition of proximal operator. In terms of optimality conditions for this problem, this means

$$0 \in \frac{1}{\gamma}(\mathbf{x}^+ - (x - \gamma f(\mathbf{x}))) + \partial g(\mathbf{x}^+) = -G_\gamma(\mathbf{x}) + f(\mathbf{x}) + \partial g(\mathbf{x}^+)$$

or equivalently $G_\gamma(\mathbf{x}) \in f(\mathbf{x}) + \partial g(\mathbf{x}^+)$. If $\mathbf{x} = \mathbf{x}^+$, and hence $G_\gamma(\mathbf{x}) = G_\gamma(\mathbf{x}^+) = 0$, this implies

$$0 \in f(\mathbf{x}^+) + \partial g(\mathbf{x}^+) = \partial f(\mathbf{x}^+) + \partial g(\mathbf{x}^+) = \partial h(\mathbf{x}^+)$$

so \mathbf{x}^+ is a minimizer of h .

References